

We will discuss and define three types of

sampling models:

1. Impulse Sampling
2. Natural Sampling
3. Flat Top Sampling

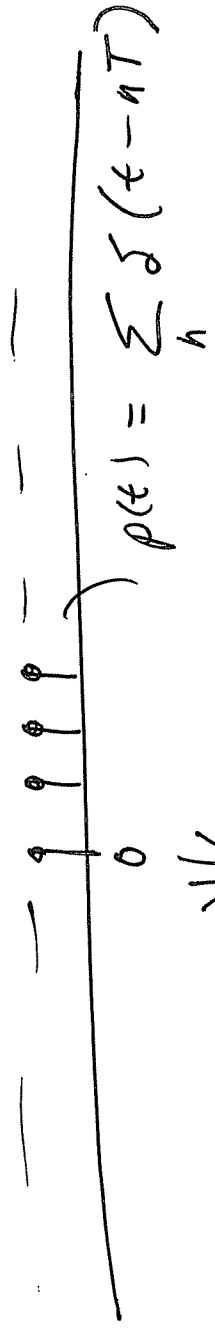
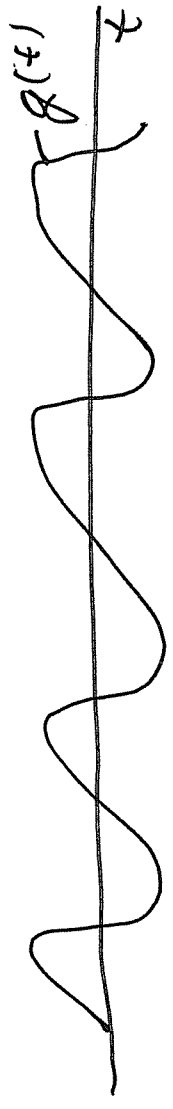
Impulse sampling

Consider a CT signal $g(t)$

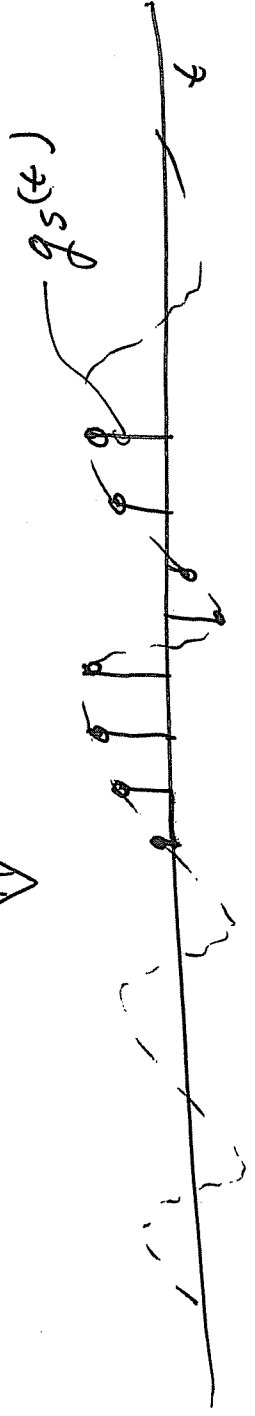
We impulse sample $g(t)$, by multiplying $g(t)$ by a train of dirac delta functions $s(t)$.

$$g_s(t) = g(t) \sum_n \delta(t - nT) \quad \text{where } T \text{ is the sample period.}$$

EX:



⇓



The DT values $g[n]$ are the non-zero values of $g_s(t)$ d.t. $g[n] = g_s(nT)$

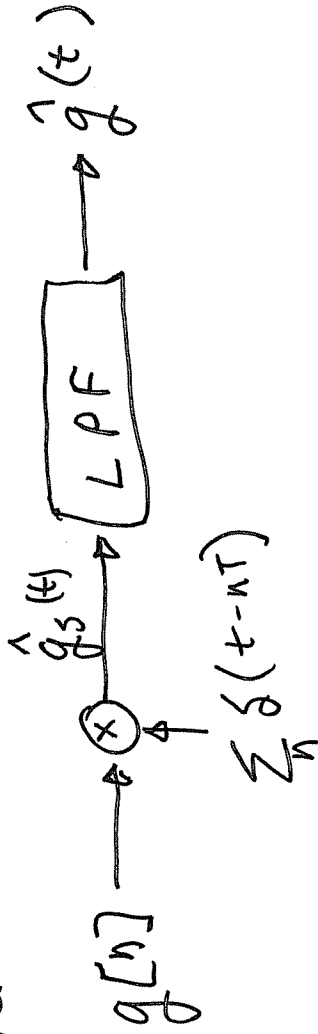


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To convert $g[n]$ back to CT, another impulse train is multiplied A.t.

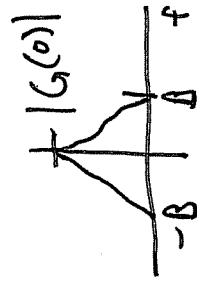
$$\hat{g}_s(t) = \sum_n g[n] \delta(t - nT)$$

The reconstructed signal $\hat{g}(t)$ is obtained by



The frequency domain reveals the limitations and capabilities of impulse sampling.

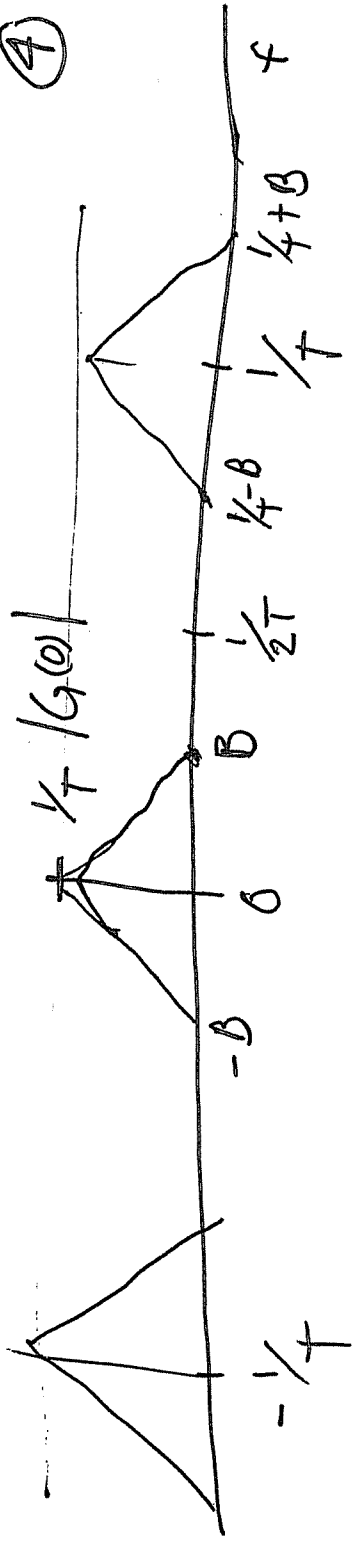
Assume $G(f)$ is bandlimited A.t.



thus $G_s(f) = G(f) * \frac{1}{T} \sum_k \delta(f - k/T)$

As $G_s(f) = \frac{1}{T} \sum_k G(f - k/T)$

4-09

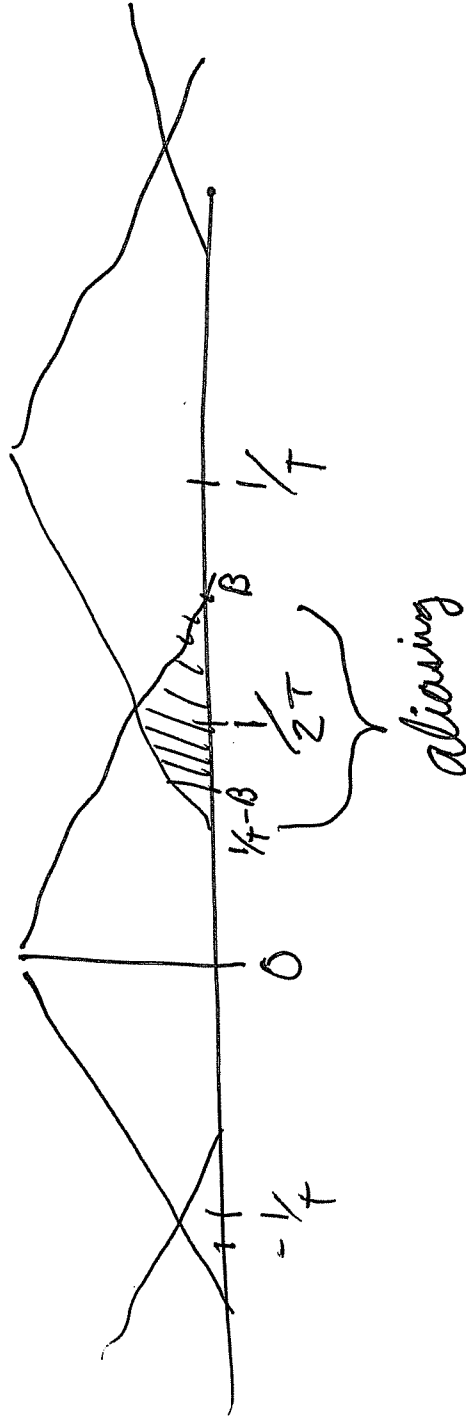


Aliasing occurs @ $B = 1/4 - B$

so no aliasing $T < 1/2B$ or

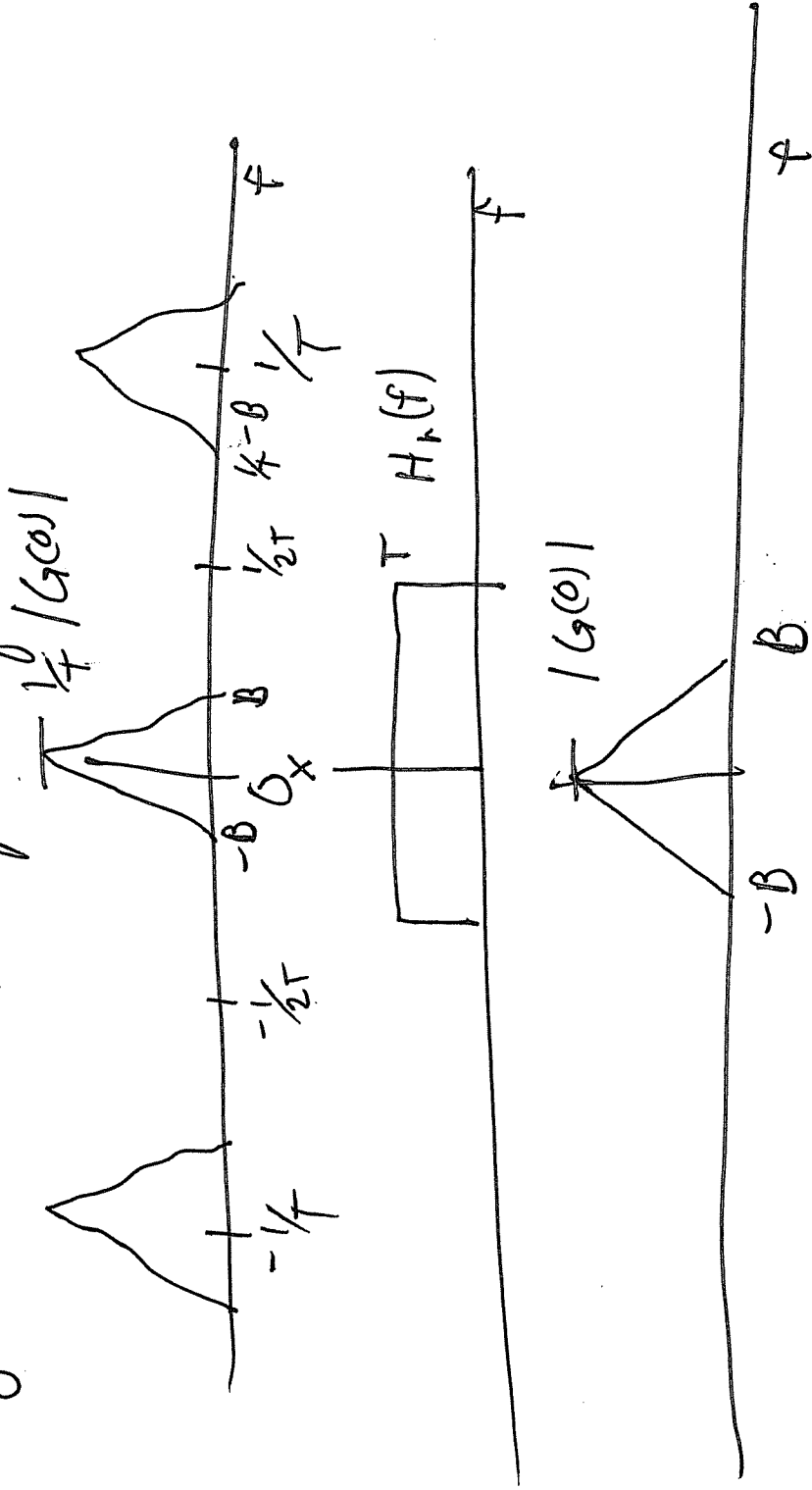
$$f_s = 1/T > 2B$$

EX: Aliasing



5-09

If there is NO aliasing we can reconstruct using an ideal low-pass filter



Note that: $g_s(t) = g(t) \sum_n \delta(t-nT)$

$$= \sum_n g(nT) \delta(t-nT)$$

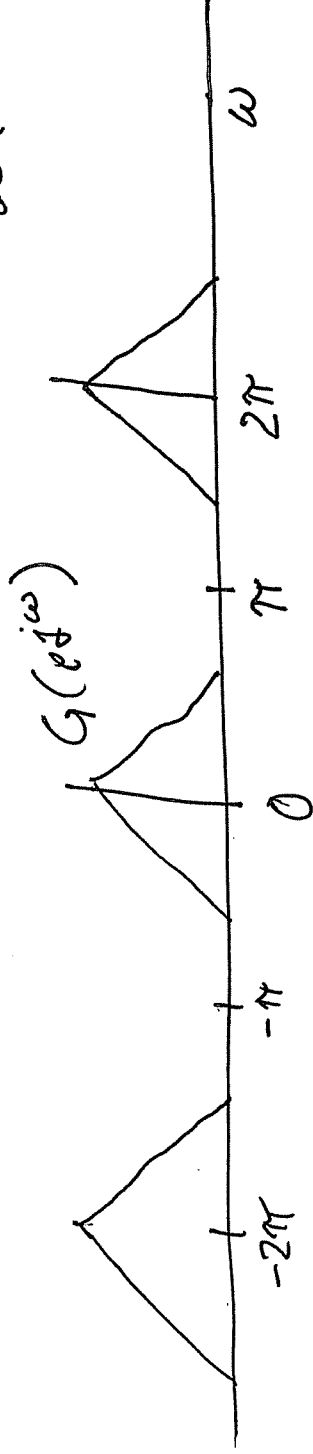
$$= \sum_n g[n] \delta(t-nT)$$

6-09

Also note: The DTFT of $g[n]$ is

$$G(e^{j\omega}) = \sum_n g[n] e^{-j\omega n} \Rightarrow \text{Note } G(z) = \sum_n g[n] z^{-n}$$

if $z = e^{j\omega}$
then $G(e^{j\omega}) = \sum_n g[n] e^{-j\omega n}$

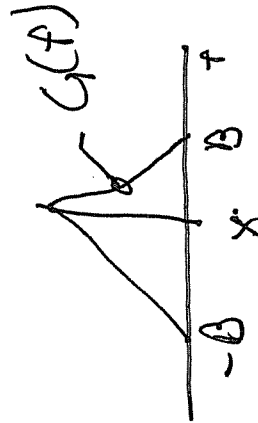
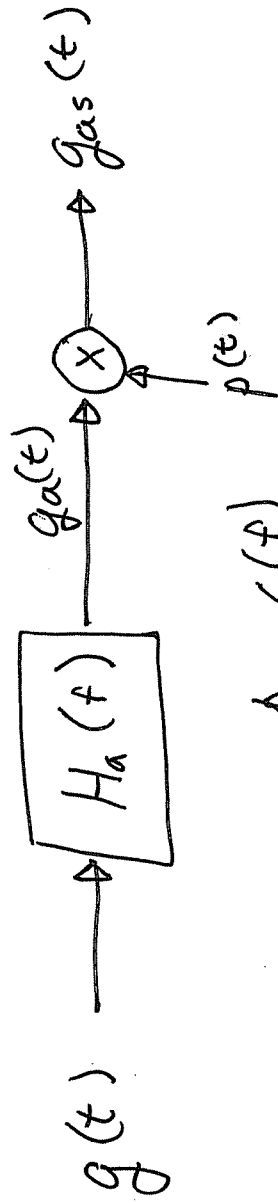


which is proportional to $G_s(f)$ for $\frac{2\pi}{T} = 2\pi$ or $T=1$

(7) - 09

Anti - Aliasing

We can prevent aliasing using anti-aliasing filter at the cost of losing bandwidth $f_s/2$.



where

