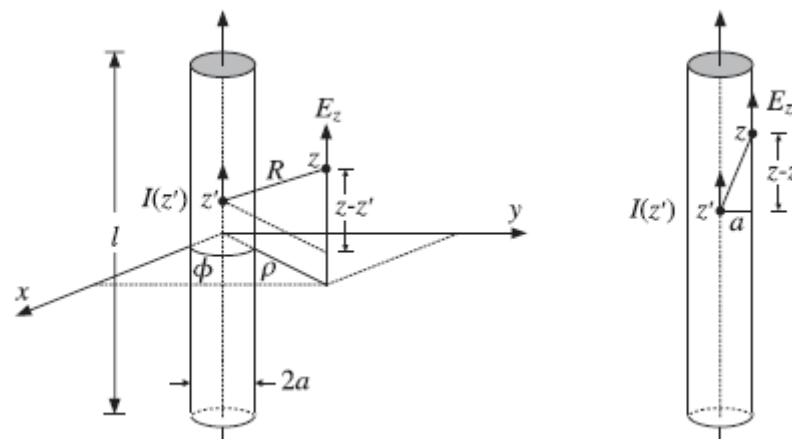


Thin Wire Antenna



- Consider a straight thin-wire antenna excited at the center by an arbitrary source
- Objective:
 - Compute the fields scattered (or radiated) by the antenna
- Solution
 - Use Hallen's equation as the base formulation
 - Derive solution to Hallen's equation
 - Use a method of moment discretization of Hallen's equation to approximate the thin-wire current

Deriving Hallen's Equation

- Hallen's equation for the straight thin wire is derived from a 1D form of the EFIE:

- $$\left[\frac{\partial^2}{\partial z^2} + k^2 \right] A_z(z) = -\frac{jk}{\eta} E_z^{inc}(z)$$

- which is essentially representative of a thin-wire kernel

- Hallen posed that the solution to this equation can be derived using the Green's function method. To this end:

- Solve the homogeneous equation

- Solve the impulse response

- Homogeneous equation solution:

- $$\left[\frac{\partial^2}{\partial z^2} + k^2 \right] A_z^h(z) = 0$$

- Has solutions:

- $$A_z^h(z) = C_1 e^{+jkz} + C_2 e^{-jkz}$$

- The forced solution is based on the impulse response:

- $\left[\frac{\partial^2}{\partial z^2} + k^2 \right] G(z) = \delta(z)$

- One form of solution to this equation can be expressed as:

- $G(z) = C_3 \sin(k|z|)$

- Note that this is continuous across $z = 0$, but has discontinuous derivatives.

- We need to solve for C_3 . To do this, plug this back into the differential equation and integrate both sides:

- $\lim_{\epsilon \rightarrow 0} \int_{-\epsilon}^{+\epsilon} \left[\frac{\partial^2}{\partial z^2} + k^2 \right] C_3 \sin(k|z|) dz = \lim_{\epsilon \rightarrow 0} \int_{-\epsilon}^{+\epsilon} \delta(z) dz$

- Differentiating, integrating by parts, leads to:

- $\lim_{\epsilon \rightarrow 0} kC_3 \left[-\cos(k(-z)) \Big|_{-\epsilon}^0 + \cos(kz) \Big|_0^{+\epsilon} + k \int_{-\epsilon}^{+\epsilon} \sin(k|z|) dz \right] = 1$

- Taking the limit $\epsilon \rightarrow 0$

- $kC_3 [2 + k \cdot 0] = 1$

- Therefore,

- $C_3 = \frac{1}{2k}$, and $G(z) = \frac{1}{2k} \sin(k|z|)$

○ Combining the homogeneous and forced solution (impulse response)

$$\blacksquare A_z(z) = C_1 e^{+jkz} + C_2 e^{-jkz} - \frac{jk}{\eta} E_z^{inc}(z) * G(z)$$

$$\blacksquare A_z(z) = C_1 e^{+jkz} + C_2 e^{-jkz} - \frac{jk}{\eta} \int_{-\frac{L}{2}}^{\frac{L}{2}} E_z^{inc}(z') G(z, z') dz'$$

○ We recall that if the current carries a current $I(z)$, the magnetic vector potential is also expressed as

$$\blacksquare A_z(z) = \int_{-\frac{L}{2}}^{\frac{L}{2}} I(z') \frac{e^{-jkR_{TW}}}{4\pi R_{TW}} dz'$$

▪ where

$$\bullet R_{TW} = \sqrt{(z - z')^2 + a^2}$$

○ Therefore, Hallen's equation is expressed as:

$$\blacksquare \int_{-\frac{L}{2}}^{\frac{L}{2}} I(z') \frac{e^{-jkR_{TW}}}{4\pi R_{TW}} dz' = C_1 e^{+jkz} + C_2 e^{-jkz} - \frac{jk}{\eta} \int_{-\frac{L}{2}}^{\frac{L}{2}} E_z^{inc}(z') G(z, z') dz'$$

Hallen's Equation

$$\int_{-\frac{L}{2}}^{\frac{L}{2}} I(z') \frac{e^{-jkR_{TW}}}{4\pi R_{TW}} dz' = C_1 e^{+jkz} + C_2 e^{-jkz} - \frac{jk}{\eta} \int_{-\frac{L}{2}}^{\frac{L}{2}} E_z^{inc}(z') G(z, z') dz'$$

- Advantages of Hallen's equation:
 - Removed the derivatives of the scalar potential
 - Smoother kernel
 - Fredholm integral equation (improved conditioning)
- Disadvantages
 - Restricted to straight wires
 - Restricted to the thin-wire kernel
 - Two additional degrees of freedom to solve for
- Solution:
 - Solution can be derived via a method of moment expansion of the current and a moment testing.
 - Due to the smoothness of the kernel, one can choose pulse basis and point matching as the lowest order approximation

Solving Hallen's Equation with PulseBasis/Point Matching

○ Discretization

- Discretize the straight wire into N linear edges, each with length $\Delta L = L / N$
- Expand the current with pulse basis functions weighted by unknown constant coefficients α_n

- $I(z) \approx \sum_{n=1}^N \alpha_n P(z; z_n, z_{n+1})$

- Perform the inner product of Hallen's equations with delta-test fns:

- $T_m(z) \approx \delta(|z - z_m^c|)$, where z_m^c is the center of the m -th cell

$$\sum_{n=1}^N \alpha_n \int_{z_n}^{z_{n+1}} \frac{e^{-jkR_m}}{4\pi R_m} dz' = C_1 e^{+jkz_m} + C_2 e^{-jkz_m} - \frac{j}{2\eta} \int_{-\frac{L}{2}}^{\frac{L}{2}} E_z^{inc}(z') \sin(k|z_m^c - z'|) dz'$$

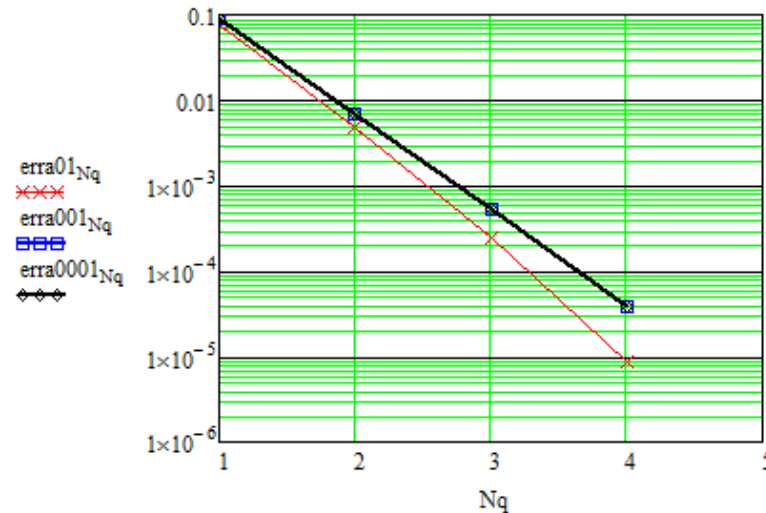
- where

- $R_m = \sqrt{(z_m^c - z')^2 + a^2}$

- The impedance matrix can be constructed from:

$$\bullet \int_{z_n}^{z_{n+1}} \frac{e^{-jkR_m}}{4\pi R_m} dz' = \begin{cases} \int_{z_n}^{z_{n+1}} \frac{e^{-jk\sqrt{(z_m^c - z')^2 + a^2}}}{4\pi\sqrt{(z_m^c - z')^2 + a^2}} dz', & m \neq n \\ \frac{1}{4\pi} \ln \left[\frac{\sqrt{1 + 4a^2 / \Delta L^2} + 1}{\sqrt{1 + 4a^2 / \Delta L^2} - 1} \right] - \frac{jk\Delta L}{4\pi}, & m = n \end{cases}$$

- where the non-self-term can be computed via a Gauss-quadrature rule
- Error in the numerical quadrature evaluation of the non-self-terms:
 - $L = \lambda/2$, $N = 20$, and $a = 0.01L, 0.001L, 0.0001L$

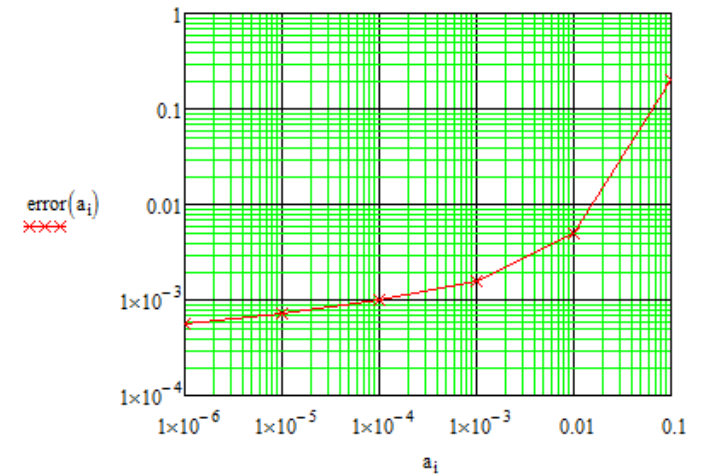


○ The self term is approximated as:

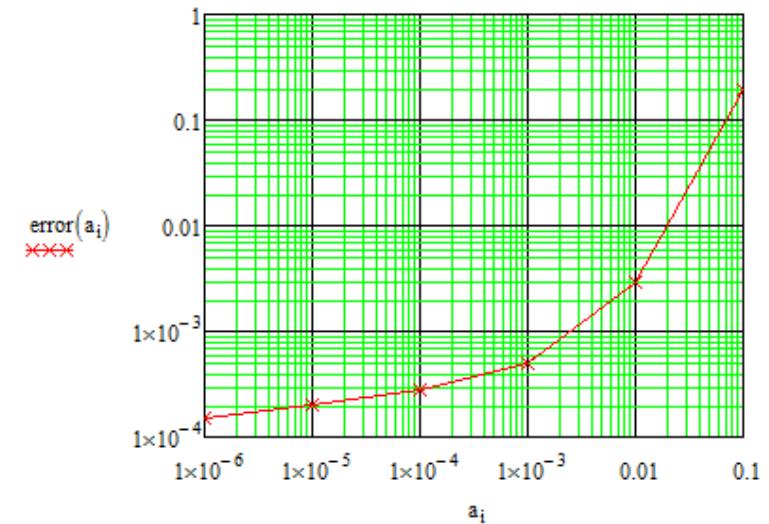
$$\blacksquare \int_{z_n}^{z_{n+1}} \frac{e^{-jkR_n}}{4\pi R_n} dz' \approx \frac{1}{4\pi} \ln \left[\frac{\sqrt{1+4a^2 / \Delta L^2} + 1}{\sqrt{1+4a^2 / \Delta L^2} - 1} \right] - \frac{jk\Delta L}{4\pi}$$

○ Example:

- $L = \lambda / 2$, $N = 10$ segments ($\Delta L = 0.05\lambda$)
 - Error in the self-term approximation:



- $L = \lambda / 2$, $N = 20$ segments ($\Delta L = 0.05\lambda$)



- Note: the impedance matrix leads to an $N \times N$ linear system of equations
 - However we have $N + 2$ degrees of freedom!!
 - We need 2 more constraints
- Constrain that $I\left(-\frac{L}{2}\right) = 0$, and $I\left(+\frac{L}{2}\right) = 0$
 - In our discrete approximation:
 - $I\left(-\frac{L}{2}\right) \approx \sum_{n=1}^N \alpha_n P\left(-\frac{L}{2}; z_n, z_{n+1}\right) = 0$, or $\alpha_1 = 0$
 - Similarly, $\alpha_N = 0$
- Next, define the contribution from the incident field

$$\blacksquare b_m = -\frac{j}{2\eta} \int_{-\frac{L}{2}}^{\frac{L}{2}} E_z^{inc}(z') \sin(k|z_m^c - z'|) dz'$$

- The kernel is a smooth function, and thus can be evaluated with Gauss-quadrature, or analytically.
- **Example:** Delta Gap Source: $E_z^{inc}(z') = V_o \delta(z')$

$$b_m = -\frac{j}{2\eta} V_o \sin(k|z_m^c|)$$

Discrete Hallen's Equation with PulseBasis/Point Matching

$$\int_{-\frac{L}{2}}^{\frac{L}{2}} I(z') \frac{e^{-jkR_{TW}}}{4\pi R_{TW}} dz' - C_1 e^{+jkz} - C_2 e^{-jkz} = -\frac{jk}{\eta} \int_{-\frac{L}{2}}^{\frac{L}{2}} E_z^{inc}(z') G(z, z') dz'$$

○ Finally, Hallen's equation can be expressed in matrix form:

$$\begin{bmatrix} 0 & 1 & 0 & \cdots & 0 & 0 \\ e^{+jkz_1^c} & Z_{1,1} & Z_{1,2} & \cdots & Z_{1,N} & e^{-jkz_1^c} \\ e^{+jkz_2^c} & Z_{2,1} & Z_{2,2} & \cdots & Z_{2,N} & e^{-jkz_2^c} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ e^{+jkz_N^c} & Z_{N,1} & Z_{N,2} & \cdots & Z_{N,N} & e^{-jkz_N^c} \\ 0 & 0 & 0 & \cdots & 1 & 0 \end{bmatrix} \begin{bmatrix} -C_1 \\ \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N \\ -C_2 \end{bmatrix} = -\frac{j}{2\eta} V_o \begin{bmatrix} 0 \\ \sin(k|z_1^c|) \\ \sin(k|z_2^c|) \\ \vdots \\ \sin(k|z_N^c|) \\ 0 \end{bmatrix}$$

■ Once we compute the solution vector, we can approximate the current as

- $I(z) \approx \sum_{n=1}^N \alpha_n P(z; z_n, z_{n+1})$

Schur's compliment of the matrix equation

- The system matrix has zero diagonal elements, which can lead to ill-conditioning. This can be avoided by working with the Schur's compliment of the system matrix.

- Write the matrix equation as:

- $\bar{\bar{Z}}\bar{\alpha} = \bar{\bar{s}}\bar{C} + \bar{b}$

- where $\bar{\bar{s}}$ is a $N \times 2$ matrix expressed as

$$\bar{\bar{s}} = \begin{bmatrix} e^{+jkz_1^c} & e^{-jkz_1^c} \\ e^{+jkz_2^c} & e^{-jkz_2^c} \\ \vdots & \vdots \\ e^{+jkz_N^c} & e^{-jkz_N^c} \end{bmatrix}$$

- We can then solve:

- $\bar{\alpha} = \bar{\bar{Z}}^{-1}\bar{\bar{s}}\bar{C} + \bar{\bar{Z}}^{-1}\bar{b}$

- Then, express the constraint that $\alpha_1 = 0$ and $\alpha_N = 0$ in operator form:

- $\bar{U}\bar{\alpha} = 0$, where $\bar{U} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 1 \end{bmatrix}$

- Therefore:

- $\bar{U}\bar{\alpha} = \bar{U}\bar{\bar{Z}}^{-1}\bar{\bar{s}}\bar{C} + \bar{U}\bar{\bar{Z}}^{-1}\bar{b} = 0$

- Which can be used to solve for \bar{C}

- $\bar{C} = -\left[\bar{U}\bar{\bar{Z}}^{-1}\bar{\bar{s}}\right]^{-1}\bar{U}\bar{\bar{Z}}^{-1}\bar{b}$

- Note that $[\bar{U}\bar{\bar{Z}}^{-1}\bar{\bar{s}}]$ is a 2×2 matrix, and $\bar{U}\bar{\bar{Z}}^{-1}\bar{b}$ is a 2×1 vector

○ Finally:

$$\bullet \bar{\alpha} = \bar{Z}^{-1} \left[\bar{I} - \bar{s} \left[\bar{U} \bar{Z}^{-1} \bar{s} \right]^{-1} \bar{U} \bar{Z}^{-1} \right] \bar{b}$$

○ Example:

$$\blacksquare L = 0.47 \lambda, a = 0.005\lambda, N = 81$$

$$N_c = 40 \quad \alpha_{N_c} = 0.013402396 + 4.939504807i \times 10^{-4}$$

$$Z_{in} := \frac{1}{\alpha_{N_c}} = 74.512310591 - 2.746179902i$$

