

## EE 572

### Exam II Objectives

At the time of the second exam in EE572, you should be able to perform the following objectives:

#### Exam II Objectives:

- Do all Exam I objectives!!
- Design full-order observers, improved observers, and ~~reduced-order~~ observers for discrete multi-input detectable systems.
- Understand and design deadbeat regulators/observers
- Derive and apply the separation principle
- Develop C programs to implement digital filters, controllers, and observers
- Develop C programs to implement digital lead, lag, and PID compensators
- Derive and use the bilinear transform
- Find a model for the sample-and-hold process in the  $s$ -plane and the  $Z$ -plane (make sure to divide by  $T_s!$ )
- Determine  $Z$ -plane regions to meet transient specifications
- Determine system type number in both the  $s$ -plane and the  $Z$ -plane
- Define  $K_p$ ,  $K_v$ ,  $K_a$  in the  $S$ -plane and the  $Z$ -domain
- Measure steady-state error for common inputs in both the  $s$ -plane and the  $Z$ -plane
- Obtain models for discrete systems from either time or frequency responses
- Perform root locus lead compensation on sampled data systems in either the  $Z$ -plane or the  $s$ -plane
- Perform root locus lag compensation on sampled data systems in either the  $Z$ -plane or the  $s$ -plane
- Perform root locus PID compensation on sampled data systems in either the  $Z$ -plane or the  $s$ -plane
- Use other methods such as Ziegler-Nichols to tune PID compensators
- Determine the effects of sampling time on stability of 2nd order systems from a time domain point of view
- Experimentally develop Bode plots of actual open-loop sample-data systems and use them to find transfer functions
- Understand and apply the Mapping Theorem to derive the Nyquist stability criterion
- Obtain polar plots and subsequently Nyquist plots from either a Bode plot or knowledge of  $G_{zoh}(s)$
- Measure gain and phase margins both theoretically and from a Bode or steady-state sinusoidal plots
- Design simple gain and lead (not lag) compensators to meet the following criteria:
  - Steady-state error specifications
  - Frequency specifications (gain and phase margins)