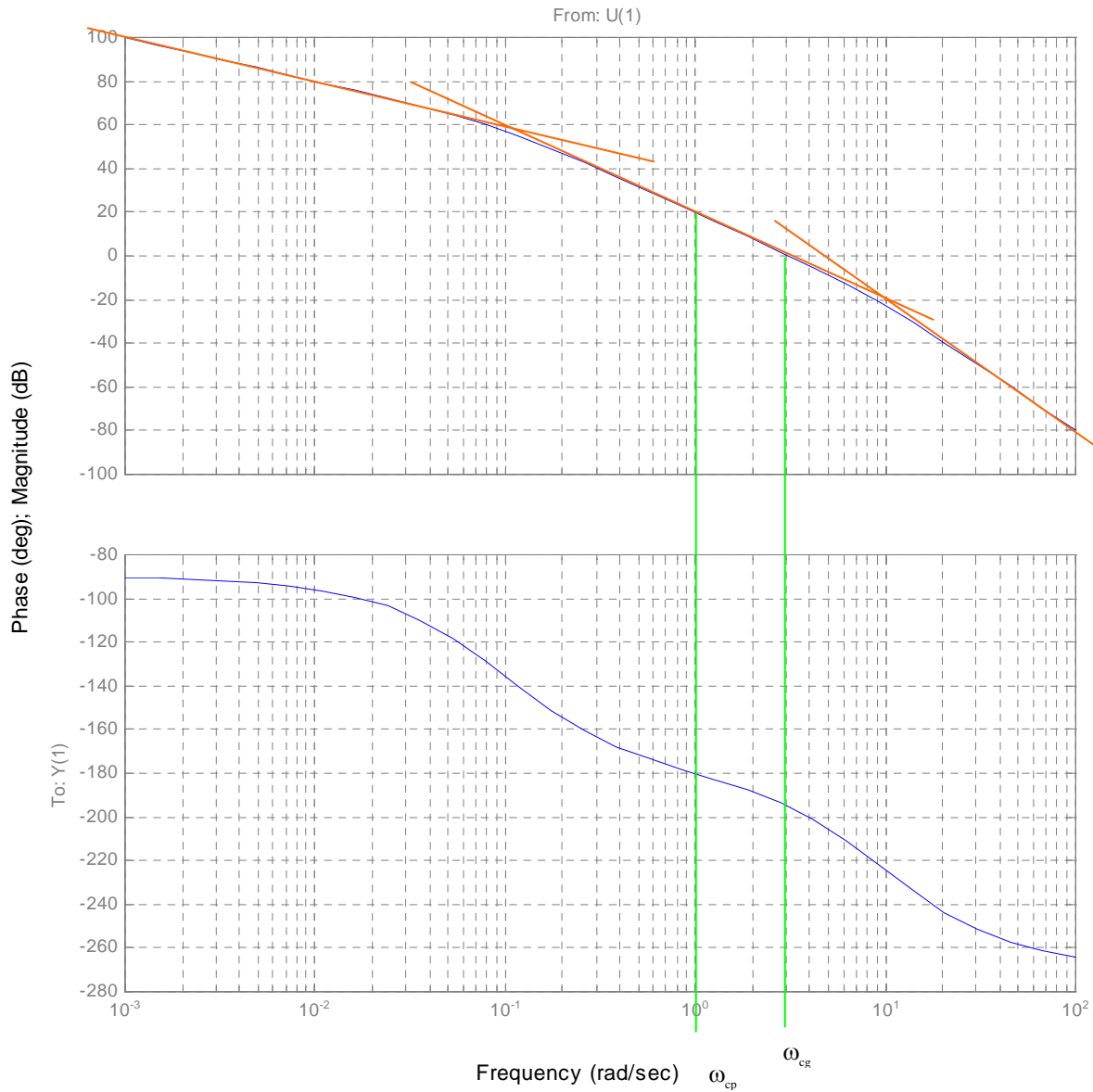


1. a) From the Bode Plot below, find  $Y(s)/W(s)=G(s)$ , the open-loop transfer function (assume  $H(s)=1$ )

Bode Plot for HW#30



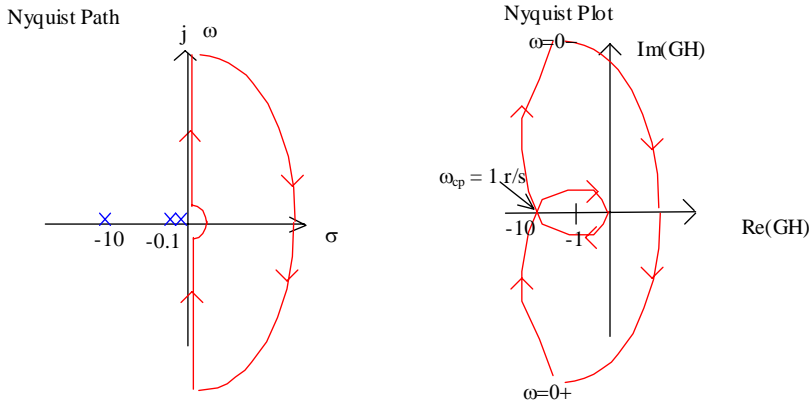
Solution:  $G(s) = 100/(10s+1)(0.1s+1)$

b) For the system in part b), find the type #,  $K_p$ ,  $K_v$ ,  $ess|_{step}$  and  $ess|_{ramp}$   
 Solution: Type # is one,  $K_p$  is infinite,  $K_v = 100$ ,  $ess|_{step} = 0$ ,  $ess|_{ramp} = 0.01$

c) Find the gain cross-over frequency ( $\omega_{cg}$ ), the phase cross-over frequency ( $\omega_{cp}$ ), the gain margin (gm) and the phase margin (pm).  
 Solution: From the Bode Plot,  $\omega_{cg} = 3.1$  rad/sec,  $\omega_{cp} = 1.0$  rad/sec and gm = -20 dB and pm = -16 degrees

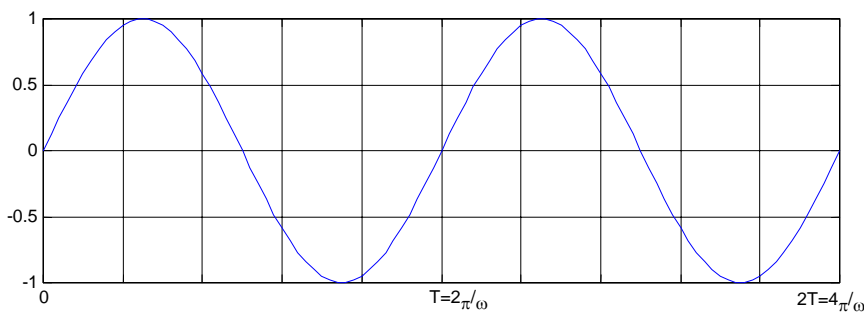
d) Draw the Nyquist path and the Nyquist Plot. How many closed-loop poles are in the RHP?

Solution



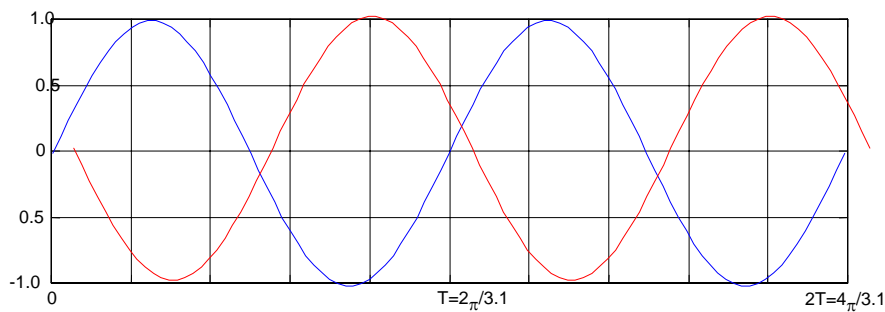
$N=Z-P = 2$ . Therefore, there are 2 RHP closed-loop poles.

e) Consider the signal  $w(t)=1\sin\omega t$  shown below:

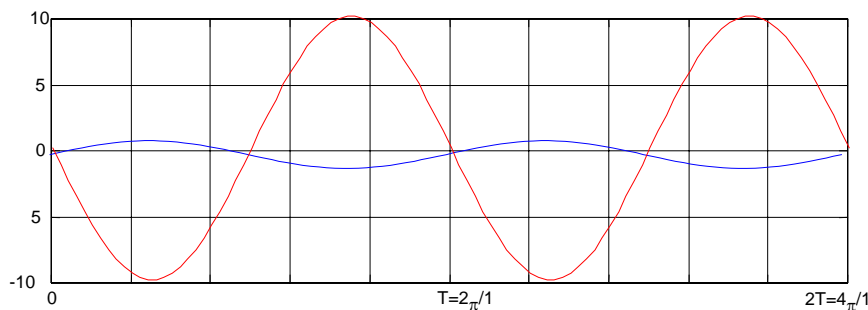


Suppose we input this signal to our OPEN-LOOP system  $G(s)=Y(s)/W(s)$ . Use the bode plot to sketch the **steady state** output  $y_{ss}(t)$  and  $w(t)$  versus time when: i)  $\omega = \omega_{cg}$  ii)  $\omega = \omega_{cp}$

Solution: At  $\omega = \omega_{cg} = 3.1$  rad/sec, the two plots have the same magnitude but the output lags the input by  $-196$  degrees ( $pm = -16$  deg.).



At  $\omega = \omega_{cp} = 1.0$  rad/sec, the two plots are 180 degrees out of phase but the output is 10 times greater than the input ( $gm = -20$  db).



f) Design the simplest compensator such that the compensated system satisfies the following specifications:

i)  $gm = 20$  dB

ii)  $pm > 10^\circ$

Solution:  $G_c = K_c = gm_{current} - gm_{desired} = -20 \text{ db} - 20 \text{ db} = -40 \text{ db} = 0.01$

g) If we use this compensator, what have you done to the steady-state error due to a ramp?

Solution: We have increased the steady-state error by a factor of 100 times!