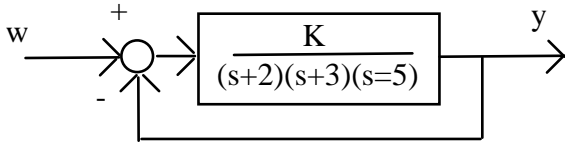
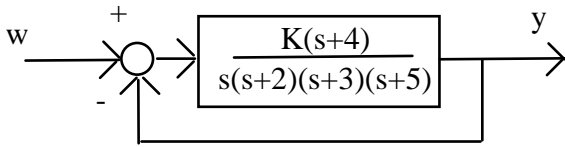


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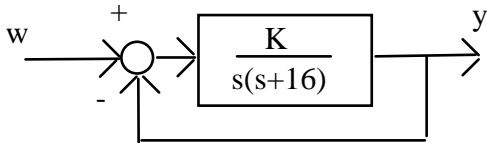
1. a) Use Routh-Hurwitz analysis to find the range on  $K$  for which the following classical control system is stable:



- b) Repeat part a) using the following system:



- c) Sketch the root locus of



(Hint: find an expression for the two poles, then substitute in various values of  $K$  from near zero to very large)

- d) Use the angle condition to determine if the following points lie on your root-locus in part c):

i)  $s = -4 + j0$     ii)  $s = 4 + j0$     iii)  $s = -8 + j2$     iv)  $s = -8.5 + j2$

- e) For those points which lie on the root locus in part d), use the magnitude condition to find the value of  $K$  which produces these closed-loop system poles